

ECR4040

nanoprecise open loop stepper rotator with integrated 1/2" aperture for endless rotation in both directions

Technology		Compatibility with Electronics	
ravel mechanism	inertial piezo drive	ECC100 piezo positioning controller	all versions
Size and Dimensions		Working Conditions	
footprint; height	40 x 40; 14.5 mm	mounting orientation	arbitrary
aperture	1/2"	working conditions	ambient
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Coarse Positioning Mode		Accuracy of Movement	
input voltage range	060 V	repeatability of step sizes	typically 5 % over full range
typical actuator capacitance	1.11µF	forward / backward step asymmetry	10%
travel range (step mode)	360 ° endless	wobble	1 mrad
typical minimum step size	0.2 m°		
maximum drive velocity (@ 45 V)	10 °/s	Position Encoder	
3(6 11)	. , .	encoder options	_
Fine Positioning Mode			
input voltage range	0 100 V		
fine positiong range	06 m°	Connectors and Feedthroughs	/RT Versions
fine positioning resolution	μ°	connector type	14-pole connector
	r		50 cm cable with connector
Materials			
positioner body	aluminum		
actuator	PZT ceramics		
connecting wires	insulated twisted pair, copper		
bearings	stainless steel		
ocugs	stamess steet		
Load (@ ambient conditions)	mounting orientation: axis vertical		
maximum load	20 N		
maximum dynamic torque around axis	2 Ncm		
Mounting			
from the top	4 through holes dia 2.2 mm, cntrbr. f. M2		
from the bottom	4 threads for M2.5 x 2 mm		
load on top	8 threads M2 x 1.8 mm		
from the side	2 threads M2.5 x 4.5 mm		
aperture	SM05 x 6.5		
Article Numbers			
/RT version	1009634		



