AMC110

1023847



Technical Specifications

Modes of Operation	
open loop positioning	stepping signals for ECS positioners
closed loop positioning	closed loop control for ECS/NUM positioners
remote operation	Ethernet Port and USB (with adapter)
Size and Dimensions	
chassis	42.7 x 28 x 4.4 cm ³
weight	approx. 4.1 kg
Controller Hardware	
power supply	100/115/230V, 50 60 Hz
connector	IEC inlet
connection cable (ELE - POS)	1 per axis, length: 2m
Software Drivers	
driver options	directly through a JSON-based REST API Wrappers for Python, LabVIEW, Matlab, C-Library (Windows/Lin), C#
Output Signals	,, , , , , , , , ,
output connectors	26-Pin SubD connector
output voltage range	stepping: 045 V; fine positioning: 045 VDC
frequency range	stepping: 0 5 kHz (1 axis); stepping: 0 2 kHz (3 axes simultaneously)
output current	stepping: max > 16 A peak
maximum capacitance load	2 μF
output noise	< 5 mVpp (500 kHz bandwidth)
resolution of signal generation	680 μV (16 bit)
Trigger Signals	
trigger level definition	LVDS, LVTTL
input trigger	1 per axis
trigger interface	GPIO - port
Features and Upgrades	
/PRO feature	enhanced functionalities and control for closed loop operation
/IO feature	realtime interfacing with external signals (through GPIO port)
/RC remote control feature	wireless control of nanopositioners
AMC/IDS closed loop feature	interferometric position control using attocube's IDS3010
Rotation Compensation feature	Feed-forward runout compensation of a rotator by two xy-stages

