

# **AMC100**

motion controller for driving up to 3 attocube Industrial Line positioners in open- or closed-loop mode in vacuum or ambient conditions

## **Technical Specifications**

### Modes of Operation

open loop positioning stepping signals for slip-stick positioners fine positioning mode for positioners closed loop positioning closed loop control for ECS/NUM positioners

remote operation Ethernet

WLAN (optional, planned)

USB for hand-held controller (optional, planned)

multi device operation control of multiple AMC100 via one PC

#### Interfaces

protocols (diff. & single ended) AquadB

trigger Directions
Step & Direction
signal levels LVDS, LVTTL

communication speed - AquadB up to 25 MHz

### **Software Drivers**

all platforms integrated Webserver (TCP/IP)

JSON
Windows 7, 8, 10 (1607)

DLL

LabVIEW<sup>™</sup>

communication speed - LabVIEW<sup>™</sup> up to 300 Hz

### Controller Hardware

size 220 x 220 x 45 mm³
weight n.n.
power supply 12 V<sub>DC</sub>, included
power consumption max. 30 W
connector for positioner 3 x D-Sub H/D 26pin
temperature range 0 - 40°C, non condensing

### Output Signals - stepping mode

stepping - voltage range 0..45 V

stepping - frequency range 0..5 kHz (1 axis), 0..2 kHz (3 axes simultaneously)

stepping - maximum current > 16 A

stepping - output noise < 5 mVpp (500 kHz bandwidth)

stepping - maximum capacitive load  $\,$  2  $\mu F$ 

### Output Signals - fine-positioning mode

fine positioning - voltage range 0..45 VDC

fine positioning - output noise < 1.3 mVpp (500 kHz bandwidth)

fine positioning - setpoint bandwidth 1 kHz



