

ANPx321/RES

Technical Specifications

Technology	
travel mechanism	inertial piezo drive
positioner type	linear
Size and Dimensions	
footprint; height	44x41.6; 11.5mm
max installation space	49.1x44; 11.5mm
weight	g
Materials	
positioner body	Titanium
actuator	PZT ceramics
connecting wires	insulated twisted pair, copper
bearings	ceramics
Options	
environmental options	/RT
Load (@ ambient conditions)	
maximum load	20 N
maximum dynamic force along the axis	2 N
Coarse Positioning Mode	
input voltage range	0 - 60 V
travel range (step mode)	15 mm
maximum drive velocity @ 300 K	approx. 3 mm/s
typical minimum step size @ 300 K	100 nm
typical minimum step size @ 4 K	20 nm

Fine Positioning Mode	
fine positioning resolution	sub-nm
fine linear positioning range @ 300 K	5 μ m
fine linear positioning range @ 4 K	0.8 μ m
input DC voltage range @ 300 K	0 - 100 V
input DC voltage range @ 4 K	0 - 150 V
Accuracy of Movement	
repeatability of step sizes	typically 5 % over full range
typ. forward / backward step asymmetry	typically 5 %
Position Encoder	
readout mechanism	resistive sensor
encoded travel range	
sensor power (when measuring)	0.01 - 1 mW
sensor resolution	approx. 200 nm
repeatability	1.2 μ m (unidirectional)
linearity (over full travel)	< 1 %
Working Conditions	
mounting orientation	axis horizontal
magnetic field range	0 - 31 T
minimum pressure (/RT)	ambient
temperature range (/RT)	273K .. 373K
Connectors and Feedthroughs	
cable	30 cm cable with connector
connector type	2-pole pin plug, \varnothing 0.5 mm, d = 2 mm
electrical feedthrough solution	VFT/LT
encoder connector	additional 3-pole plug
High Load Option (/HL)	
/HL/RT - maximum dynamic force	3 N
/HL/(U)HV - maximum dynamic force	2 N
/HL/LT - maximum dynamic force	1.5 N
Versions	
/RT version	1006350

Technical Drawings

