

### High speed positioner

#### **Concept:**

The **NanoX 400** linear stage is a development within our ultrafast **NanoX**<sup>®</sup>-line. It provides a long positioning and scanning range as well as a central aperture. Due to FEA-optimization of these stages you meet highest dynamical performance and excellent guiding accuracy. This is accomplished even with high mass loads in a compact package. Our optimization also incorporates excellent temperature compensation properties. The sophisticated monolithic guidance design of the solid flexure hinges means the trajectory is free of mechanical play and friction. The **NanoX 400** is also available with strain gauge or capacitive measurement systems.

#### **Specials:**

Vacuum and cryogenic versions are available on demand as well as body material variations of invar, super invar, aluminum or titanium.

An optional external sensor preamplifier (version "EXTERN"/"DIGITAL") offers independence from cable length.

#### **Mounting:**

The raster tapped and thru holes allow easy integration of the **NanoX400** into any application or mechanical setup.



Image: NanoX 400

#### Product highlights:

- travel range 480/400 µm open/closed loop
- sub-nm resolution
- highest dynamical performance
- excellent guidance accuracy
- central aperture of Ø 3 mm

#### Application examples:

- automation
- laser optics
- life science
- scanning systems

#### **Options:**

- vacuum version
- cryogenic version
- special materials



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### Technical data

		Unit	NanoX 400	NanoX 400 SG	NanoX 400 CAP		
Part no.		-	T-108-20	T-108-21	T-108-26		
axis		-	X				
motion open loop (±20%)*		μm	480				
motion closed loop (±0.2%)*		μm	- 400				
capacitance (±20%)**		μF	10.2				
feedback sense	or	-	-	strain gauge	capacitive		
resolution ope	n loop***	nm	0.8	0.8	0.8		
resolution clos	ed loop****	nm	-	8	2		
typ. repeatabili	ity	nm	-	80	20		
typ. non-linear	ity	%	-	0.1	0.02		
resonant frequency		Hz	400				
additional load 50 g		Hz	300				
additional load 100 g		Hz	250				
additional load 300 g		Hz	150				
stiffness		N/µm	0.4				
max. push/pull force open loop		Ν	100/100				
max. push pull force closed loop		Ν	- 16/16				
max. load		Ν	50				
lateral force limit		Ν	100				
rotational error		µrad	5 (about all axes)				
dimensions w x h x d		mm	52x32x52 52x32x70				
central aperture		mm	ø3				
voltage range		V	-20+130				
soppostor V	voltage	-	ODU series L 3 pol.				
connector	sensor	-	-	LEMO 0S.304	LEMO 0S.650		
temperature range		°C	-20+80				
material		-	stainless steel/aluminum				
weight		g	250	270	370		

\* typical value measured with ENV 40 nanoX amplifier

\*\* typical value for small electric field strength

\*\*\* The resolution is only limited by the noise of the power amplifier and metrology.

\*\*\*\* max. force, with which the system operates in closed loop within the specification



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## Drawing NanoX 400 (SG)







top view side view bottom view Ø3.2/Ø6∓28.8 (2x) motion (Ø3(2x))-(for fixing with M3 scn **v**s) X ¢ ⊕ ф top plate (moving part) Ħ ф Ø3G7∓5 (4x) bottom plate (fixing part) (pin holes) Ø3G7∓5 (4x) **D**52 32 ¢ ¢ ৻ (pin holes) Ø3 øз (free aperture) **†**@ (free aperture) 6 M3-6H∓5 (2x) Ш 24 M3-6H¥5 (2x) (tapped hole ШU (tapped hole for mounting parts) T ľ for mounting parts)

model (1:2)

open loop version without sensor cable, standard cable length 1m closed loop version with standard cable length 1.2m (EXT/DIG 2m)

	T-108-2x		nanoX 400 (SG)	
unit [mm]	nie name PT10821		OK: date/sign.	
tapped hole tolerance ± 0.02	$\ominus \oplus$	scale 1:1	customers drawing piezosystem jena	



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### Drawing NanoX 400 CAP





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